The Application of AHP to the Evaluation of General Performance Engineering Machinery

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ABSTRACT

In this paper we provide with a system of evaluated indexes of general machinery performances basing on the AHP. The hierarchy structure of the evaluated indexes system is discribed in detail in the first section. Then we calculated the priorities of the evaluated indexes combined with fuzzy membership and recommanded the indexes to evaluate general machinery performances. In the final section we illustrate some examples as the evaluations of caterpillar and wheeled bulldozers.

I. Introduction

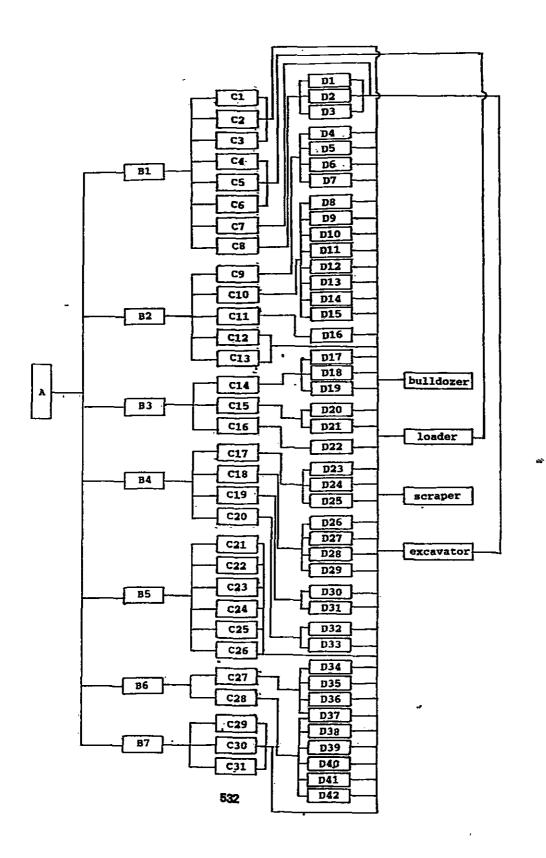
The evaluation of general performance of engineering machinery is both a qualitive and quantitative problem. The AHP can solve such problem effectively by structuring a hierarchy of indexes system and by eliciting judgments to develop priorities of the indexes. It thus combines the index system with practial evaluated problem. In this paper we studied the engineering machinery using the AHP by first defined the situation carefully, including as many relevant details as possible, then structured it into a hierarchy of levels of detail indexes (Figure 1). We then established relationships between the elements of each level of the hierarchy by comparing the elements in pairs and quantitate fuzzy indexes. So that the established index system is of practical value. By doing so we provided a structured hierarcal model, calculated the priorities and applied the concepts of fuzzy membership in the quantitative theory. We also illustrate the practical value of the above method with a real-fife application and the result shows reliablisity.

II. Evaluated System Indexes and Model

We began by laying out the related elements, which attribute to the general performance, of the engineering machinery as a hierarchy. We then made paired comparisons among the elements of a level as required by the criteria of the next higher level. These comparisons gave rise to priorities and finally, through systthesis, to arrive the global priorities. The number of elements that is chosen are no more than desired to represent the general performance. We thus gave a hierarchical indexes system of general performence evaluation of bulldozers.

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A general performance B2 B1 operation performance flexible performance generalized reliability **B**3 safety performance B4 **B**5 protection performance **B6** man-machine performance B7 economic performance C1 effective operation ability **C2** operation hitch C3 rate of shearing force C4 digging power C5 height of unloading-loading C6 distance of unloading-loading **C7** rate of efficacy C8 operation range C9 power property C10 passable property , C12 smooth-going property average velocity C11 C13 maximum travel C14 direction steadiness indination-resistant property C16 C15 brake property C17 reliability C18 maintainable property C19 durability C20 effectiveness C21 discovery defence C22 hit defence C23 puncture defence C24 destroy defence C25 tri-defence performance C26 shrapnel defence C27 operation property C28 comfortable property C29 C30 purchasing cost development cost C31 cost of guarantee application D1 height of operation D2 radius of operation D3 D4 maximum road velocity depth of operation **D**5 D6 maximum slope-velocity acceleration time **D7** maximum degree of climbing a slope **D**8 loose pavement velocity **D**9 minimum road clearance D11 angle of departure D10 angle of approach D12 minimum radius of turning height of overcoming vertical tower D13 average width of horizontal trench D14 average angular velocity of changing direction D15 allowance velocity of vibration D16 adhesive weight of travelling D17 rate of the slanting distance and travel D18 frequency of operation with definitive travel D19 maximux angle of cross wise slope D20 turning angle of cross wise slope D21 D23 average life-span D22 distance of brake D25 degree of reliability unefficient rate D24 D26 average time of repair D27 rate of maintenance degree of maintenance D28 average time of preventing maintenance D29 average working time of first hitch D30 D31 lift-span limit inherent degree of effectiveness D32 reachable degree of effectiveness D33 D35 visible property D34 portable property property of the field of vision D36 D37 space property average square value of accelation D38 D40 aritight property D39 voice D42 exit-entrance D41 tempreratuse

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III. Priorities of Varying Indexes

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The reasonableness of priorities of indexes is mainly determined by the pairwise comparison matrix against one critrion in a reasonable structural hierarchical evaluated indexes system. To maintain this reasonableness, we must make good use of people's experiences and judgments. So we structured two kinds of comparison matrix. One is basing on the general judgments of decision makers, as in the second level, which requires more consideration on policy but less on specialty. In our application we consulted 47 experts and decision makers of 29 units. The results is of a 86% consistencey in the ranking of indexes. The other is determined through discusions of our research group, and through further consulting the experts, as in the third and fourth level, and thus guaranteed the validity of the comparison matrix. In this way we can maintain reasonableness of the calculated priorities of the indexes. The result of the calculation of indexes indicated such consistency.

The comparison matrices of the above engineering machinery application are omitted here.

IV. Quantitating the Value of Indexes and Linear Weighted and Ideal Point Methods

Because 58 evaluating indexes are different in dimension, functional relations and are of different types, so they are not comparable. We have to quantitating the value of each index in order to synthesize a single goal system, its quality can thus be judged generally. So to evaluate the general performance of engineering machinary using the AHP, we need not only to calculate the priorities of each index but also to quantitatly the differnt values of each index. We use the membership function, also called utility function to mechanical system, to realize this quantitation. It indicates the relation between the contribution of each index to the general performance and the index value.

Suppose the index function of plan j is e = f(x), (i=1,2,...,m)i i The minimum value is m, the maximum is M. Generally, the index i function set F(x) can be divided into three subsets: . F(x) = $\{f(x), f(x), ..., f(x)\} = f(x) \cup f(x) \cup f(x),$. j 1 2 m q h s . (j=1,2,...,n)The f(x), (g=1,2,...,G) includes those indexes which have the g feature of the greater the value the greater the contribution. The subset f(x), (h=G+1,...,H) is formed by those indexes with h

the property of the greater the value the smaller the contribution. The subset f(x), (s=H+1,...,m) includes middle s

value of the indexes. Suppose the membership function is linear, we give the membership function of the above three index subsetsa as following: (Figure 2)

Maximum Type: (i=1,2,...,G)

Minimum Type: (i=G+1,...,H)

Middle Type: (i=H+1,...,m)

 $B(e) = \begin{pmatrix} 2(e - m) & M - m \\ i & i \\ ---- & (m_i \leq e_i < ----) \\ M - m & (m_i \leq e_i < ----) \\ 2 & M - m & 2 \\ ---- & (m - e + m) \\ ---- & (m - m + m + m) \\ 1 & 1 & 1 \\ 0 & (e < m, e > M) \\ 1 & 1 & 1 & 1 \end{pmatrix}$

The membership function can be of different shape. So we can see that to quantitating the evaluating indexes we

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should give the membership function of each kind of indexes and decide the minimum value m and the maximum value M .

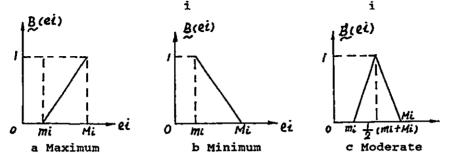


Figure 2 The Linear Membership Function

Follow the above process we can compare between the indexes of different dimension and make it a rule for all kinds of indexes that the greater the memebership, the contribution to the general performance.

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Basing on the above work, we can build a general performance evaluating function. We recommand "Linear Weighted Sum Function" (LWSF) method and "Ideal Point Function" (IPF) method to evaluate the general performence of engineering machinery.

1. LWSF

LWSF is given as the following:

 $U(x) = \sum_{j=1}^{m} B W$, (j=1,2,...,n) j i=1 ji ji

U (x), B , W indicate the LWFS, the membership of the ith j ji ji index and the weight of the ith index f the j plan system. respectivelly.

Thus we transfer the multi-objective decision problem V-max F (x) x R i into a single-objective maximizing problem U (x). We can give j global ranking of the plan system according to the value of U (x). When the two U (x) values are close, we can construct j j twice evaluating function and evaluate it the second time. Or we can reevaluate it through other evaluating function.

2. IPF

The evaluation function of IPF type is as following:

 $y(x) = 1 - \sum_{i=1}^{m} w (1-B)^{2}$, (j=1,2,...,n)

y(x) indicates the membership of plan j to ideal plan (y(x)=1). j We can rank all plan system according to the value of y(x).

V. The Application of the Method to General Porformance of Engineering Machinery _ and Its Results

Using the above evaluating model of general performance of engineering machinery, we evaluated four kinds of bulldozers T74, T85 (wheeled bulldozers), T81, T82 (caterpullar bulldozers).

1. The evaluating results are as follows:

In Table 1 we can see that the results is close to real neasurement value. The error is less than 10%.

In Table 2 we can conclude that most indexes of T82 are better than that of T81.

In Table 3 we find that the reliability and economical indexes of T74 is far better than that of the other three bulldozers.

2. The calculation of subindexes system

We find in Table 4 that calcultions of subindexes system are in consistant with the results of the evaluating index systems above. The calculations also indicate the quality of index and subindex system and thus help in disigning a new plan and improving product.

3. Evaluating results of general performance system

See Table 5.

4. The results of flexibility (Table 6)

The result in Table 6 indicates that the general performance of T85 will be far better than that of T74 provided which provided us to improve the level of reliability of T85 to that of T74.

Table 1The Comparison of the Calculating Valueand the Practical Value

, Indices	-	1	т 74	1	т 85	l l	т 81-	T 82.	
	Calculating Values Practical Values	i I	82790 83300	1	125572 141120	1	158802 151802	162128 155330	8 0
	Calculating Values Practical Values	1	51.21 52.00				42.81 44.25		

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Table	2	Т	he	Compar	ison	of	the	Index	Values	
		of	T82	and	т81	Bu]	Lldos	zers		

Models	I T	T	i Models	Н. Т	т	ł
Indices	82	81	Indices	1 82	81	ļ
C1 (N)	162128	158802	(C2(m ³ /h)	146	98	
C3(N/m)	41442	39210	1 D4(Km/h)	47	43	
D6 (Km/h)	35	29	D8(Km/h)	47	46	
1 D9'(m)	.415	.400	1 D10(o)	1 38	28	1
D15(1/sec)	.599	.446	D16(Km/h)	1 47	43	f
l C12(Km/h)	32	29	C13(Km)	1 204	184	ſ
D23(h)	1 34	21	1 D24(1/h)	029	.047	ł
D25(Probability)	.49	.32	1 D30(h)	I 77	30	ł
D32(Ratio)	.93	.90	D33(Ratio)	1.90	.87	ł
1 D38(m/S ²)	1-093	1.136	<pre>(C21(Probability)</pre>	1.0054	.0017	ſ
C22(Probability)		.116	[C23(Probability)	1.0536	.0390	I
C24 (Probability)	.943	.871	<pre>IC26(Probability)</pre>	.741	.625	ł
D35(Ratio)	80	29	$I = T^{29}(10000 \text{ Y})$	1 69	101	ļ
C30(10000 Y)	22	27	1 D7 (o)	21	36	1
D11(o)	27	36	D12(m)	1 4.47	2.42	1
D26(h)	2.69	2.34	D29(h)	1 2.75	2.35	1
D34(Ratio)	.847	.525	1 D37(m ²)	1 ⁷ 2.56	2.64	l
l D39(dB)	101	97	C31(Y/Workshop)	1 513	440	1
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Table	-3	The Comparison of T74 and the Bulldozers	
		of Other Three Kinds	

Model:	s	т	I	T	1	т	í T	
Indices	1	74	1	85	1	81	82	
C1 (N)	1	82790		125572	!-	15880Ż	162128	
C2(m3/h)	1	38	I	71	Ĩ	98	146	5
i C-3 (N/m)	3	25953	1	38052	1	39210	4144	
D16(Km/h)	1	25	1	33	Ì	43	4	_
l D23(h)	1	. 80	1	14	1	21	⁴ 34	
D30(h)	1	102	-1	18	Ì	30	1 73	-
C29(10000 Y)	1	°57	1	84	1	101	1 69	à
C30(10000 Y)	1	16		30	<u></u>	27	1 22	
C31 (Y/Workshor) [128	Ì	267	i	440	1 513	-

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Table 4 The Evaluating Results of Every Sub-system

Sub-systems	74	85	81	82
	Style	Style	Style	Style
Operation Calculating Values		.103	.164	.239
Performance Optimal Consequence		3	2	1
Flexible (Calculating Values Performance Optimal Conseguence	.036	.044	.073 2	.077 2 1
Safety Calculating Values	.049	.062	.083	.077
Performance Optimal Consequence	4	3	2	1
Reliability Calculating Values	.158	.030	.062	.094
Optimal Consequence	1	4	3	2
Protection [Calculating Values]	.010	.005	.018	.027
Performance[Optimal Consequence]		4	2	1
Man-machine Calculating Values Performance Optimal Consequence	.042	.059 2	.062 1	 .051 3
Economic (Calculating Values	.083	.043	.021	.020
Performance(Optimal Consequence)	1	2	3	4

Table 5 The Calculating Results of Three Different Kinds of Methods

Models Methods	т 74	ГТ 1 85	т 81	т 82	Types of Values
Linear Weighted Sum Method	.584	.483		. 346	the bigger, l
Ideal Point Method	.504	.413	.309	. 295	the bigger, the better.
Suppositional Object Method	.437	 .518	.587	.619	the smaller

Table 6 The Calculating Results of Sensitivity by Means of the Linear Weighted Sum Method

Models	 T 85		
Calculating Values		•	• •
Optimal Consequence			i 1 !

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VI. Conclusions

By using the evaluating model of the general performance system. has been proved that the calculated values of the evaluated it the evaluated results of the sub-performance system. indices. that of the general performance system and that of sensitivity all accord with the actual situation, and the quantitative analysis coincides perfectly with the qualitative analysis. The quantitative analytic results of the model shows us not only the priorities of the sub-system performance and the gereral performance, but also the reasons for priorities. It points out the direction for the improvement and decision of the plan system, and provides quantitative basis. The model is able to evaluated indices and system evaluating method flexibly, choose and able to have sensitivity analysis. It has great flexibility strong suitability. The model is able to evaluate not only and wheeled and caterpillar engineer machinery but also the the wheeled and caterpillar vehicles. This evaluating method is common to other specialized subjects and multiobjective decision making. So it has wide common use. It is a new and effective means of system proof and decision making scientifically.

References

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